# Structural Analysis Lecture Series



## SA61: Three-Moment Equation: Part II

### Analysis of Continuous Beams with Support Settlement

This document is a written version of video lecture SA61, which can be found online at the web addresses listed below.

#### **Educative Technologies, LLC**

http://www.Lab101.Space https://www.youtube.com/c/drstructure

#### Structural Analysis – SA61 The three-moment equation for the analysis of continuous beams with support settlement

**Prerequisite: Lecture SA60** 

The three-moment equation is a single algebraic expression that establishes a relationship among the moment values at three consecutive points in a beam. Lecture SA60 covered the use of the three-moment equation for analyzing beams with no support settlements. This lecture expands the previous discussion by introducing support settlements into the equation.

Consider the continuous two-span beam shown below.



Figure 1: A two-span beam

Suppose segments AB and BC are subjected to a counterclockwise rotation caused by support displacements at B and C, as depicted in Figure 2.



Figure 2: A two-span beam with support settlements

The differential vertical displacement in segment AB, denoted by  $\Delta_{\rm B/A}$ , is the difference between the settlements at A and B. Similarly,  $\Delta_{\rm C/B}$  denotes the differential vertical displacement for segment BC. These differential displacements, which represent the support settlements, can be introduced in the three-moment equation via the slope-deflection formulation.

The generalized form of the slope-deflection equations for segment AB are given below.

$$M_{AB} = \frac{2EI_{AB}}{L_{AB}} (2\theta_A + \theta_B - \frac{3\Delta_{B/A}}{L_{AB}}) + \Omega_{AB}$$
[1]

$$M_{BA} = \frac{2EI_{AB}}{L_{AB}} (\theta_A + 2\theta_B - \frac{3\Delta_{B/A}}{L_{AB}}) - \Omega_{BA}$$
[2]

In the above equations,  $\Omega$  symbolizes fixed-end moments.

For member BC, the slope-deflection equations can be written as follows.

$$M_{BC} = \frac{2EI_{BC}}{L_{BC}} (2\theta_{B} + \theta_{C} - \frac{3\Delta_{C/B}}{L_{BC}}) + \Omega_{BC}$$
[3]

$$M_{CB} = \frac{2EI_{BC}}{L_{BC}} (\theta_{B} + 2\theta_{C} - \frac{3\Delta_{C/B}}{L_{BC}}) - \Omega_{CB}$$
[4]

Figure 3 shows two different representations of the member-end moments. In Figure 3a, the moments are shown using the three-moment equation sign convention. Figure 3b shows the moments using the slope-deflection sign convention.



Figure 3: Moment representations for the three-moment and slope-deflection formulations

Comparing the two sets of moments, we can see that:  $M_{AB} = -M_A$ ,  $M_{BA} = M_B$ ,  $M_{BC} = -M_B$ , and  $M_{BC} = M_C$ . Therefore, the following joint equilibrium equations hold true.

$$M_{AB} = -M_A$$
 [5]

$$M_{BA} + M_{BC} = 0$$
 [6]

$$M_{CB} = M_C$$
[7]

By substituting the slope-deflection equations in Equations [5], [6], and [7], the following equations result:

$$M_{A} + \frac{2EI_{AB}}{L_{AB}} (2\theta_{A} + \theta_{B} - \frac{3\Delta_{B/A}}{L_{AB}}) + \Omega_{AB} = 0$$
[8]

$$\frac{2\mathrm{EI}_{\mathrm{AB}}}{\mathrm{L}_{\mathrm{AB}}}(\theta_{\mathrm{A}}+2\theta_{\mathrm{B}}-\frac{3\Delta_{\mathrm{B/A}}}{\mathrm{L}_{\mathrm{AB}}})+\frac{2\mathrm{EI}_{\mathrm{BC}}}{\mathrm{L}_{\mathrm{BC}}}(\theta_{\mathrm{C}}+2\theta_{\mathrm{B}}-\frac{3\Delta_{\mathrm{C/B}}}{\mathrm{L}_{\mathrm{BC}}})+\Omega_{\mathrm{BC}}-\Omega_{\mathrm{BA}}=0$$
[9]

$$-M_{\rm C} + \frac{2EI_{\rm BC}}{L_{\rm BC}} (2\theta_{\rm C} + \theta_{\rm B} - \frac{3\Delta_{\rm C/B}}{L_{\rm BC}}) - \Omega_{\rm CB} = 0$$
[10]

We can determine the slopes at A, B, and C ( $\theta_A$ ,  $\theta_B$ , and  $\theta_C$ ) by solving Equations [8], [9], and [10] simultaneously. The resulting algebraic expressions for the three slopes are given below.

$$\theta_{A} = \frac{3I_{BC}\Delta_{B/A}}{2(I_{BC}L_{AB} + I_{AB}L_{BC})} - \frac{I_{BC}L_{AB}^{2}(\Omega_{AB} + M_{A})}{4EI_{AB}(I_{BC}L_{AB} + I_{AB}L_{BC})} - \frac{I_{BC}L_{AB}\Delta_{C/B}}{2L_{BC}(I_{BC}L_{AB} + I_{AB}L_{BC})} - \frac{I_{AB}L_{BC}\Delta_{B/A}}{2L_{BC}(I_{BC}L_{AB} + I_{AB}L_{BC})} - \frac{I_{AB}L_{BC}(4\Omega_{AB} + 2\Omega_{BA} - 2\Omega_{BC} - \Omega_{CB} + 4M_{A} - M_{C})}{12E(I_{BC}L_{AB} + I_{AB}L_{BC})}$$
[8]

$$\theta_{\rm B} = \frac{(I_{\rm BC}L_{\rm AB}^2\Delta_{\rm C/B} + I_{\rm AB}L_{\rm BC}^2\Delta_{\rm B/A})}{L_{\rm BC}L_{\rm AB}(I_{\rm BC}L_{\rm AB} + I_{\rm AB}L_{\rm BC})} + \frac{L_{\rm AB}L_{\rm BC}(\Omega_{\rm AB} - \Omega_{\rm CB} + \Omega_{\rm BA} - \Omega_{\rm BC} + M_{\rm A} - M_{\rm C})}{6E(I_{\rm BC}L_{\rm AB} + I_{\rm AB}L_{\rm BC})}$$
[9]

$$\theta_{\rm C} = \frac{3I_{AB}\Delta_{\rm C/B}}{2(I_{BC}L_{AB}+I_{AB}L_{BC})} + \frac{I_{BC}L_{AB}\Delta_{\rm C/B}}{L_{BC}(I_{BC}L_{AB}+I_{AB}L_{BC})} - \frac{I_{AB}L_{BC}\Delta_{\rm B/A}}{2L_{AB}(I_{BC}L_{AB}+I_{AB}L_{BC})} - \frac{I_{AB}L_{BC}\Delta_{\rm B/A}}{2L_{AB}(I_{BC}L_{AB}+I_{AB}L_{BC})} - \frac{I_{AB}L_{BC}\Delta_{\rm B/A}}{2L_{AB}(I_{BC}L_{AB}+I_{AB}L_{BC})} - \frac{I_{AB}L_{BC}\Delta_{\rm B/A}}{12E(I_{BC}L_{AB}+I_{AB}L_{BC})} - \frac{I_{AB}L_{BC}\Delta_{\rm B/A}}{4EI_{BC}(I_{BC}L_{AB}+I_{AB}L_{BC})} - \frac{I_{AB}L_{AB}\Delta_{\rm B/A}}{4EI_{AB}L_{AB}} - \frac{I_{AB}L_{AB}}{4EI_{AB}L_{AB}} - \frac{I_{AB}L_{AB}}{4EI_{AB}} - \frac{I_{AB}L_{AB}}{4EI_{AB}} - \frac{I_{$$

Substituting Equations [8] through [10] in Equation [2] results in Equation [11].

$$M_{BA} = \frac{6EI_{AB}I_{BC}(\Delta_{C/B}L_{AB} - \Delta_{B/A}L_{BC})}{2L_{AB}L_{BC}(I_{BC}L_{AB} + I_{AB}L_{BC})} - \frac{L_{AB}I_{BC}(\Omega_{AB} + 2\Omega_{BA} + M_{A}) + L_{BC}I_{AB}(2\Omega_{BC} + \Omega_{CB} + M_{C})}{2(I_{BC}L_{AB} + I_{AB}L_{BC})}$$
[11]

And since  $M_{BA} = M_B$  (see Figure 3), Equation [11] can be rewritten in the following form.

$$M_{B} = \frac{6EI_{AB}I_{BC}(\Delta_{C/B}L_{AB} - \Delta_{B/A}L_{BC})}{2L_{AB}L_{BC}(I_{BC}L_{AB} + I_{AB}L_{BC})} - \frac{L_{AB}I_{BC}(\Omega_{AB} + 2\Omega_{BA} + M_{A}) + L_{BC}I_{AB}(2\Omega_{BC} + \Omega_{CB} + M_{C})}{2(I_{BC}L_{AB} + I_{AB}L_{BC})}$$
[12]

By rearranging the terms of the above equation, we can obtain the generalized form of the threemoment equation, as shown in Equation [13].

$$\frac{L_{AB}}{I_{AB}}M_{A} + 2(\frac{L_{AB}}{I_{AB}} + \frac{L_{BC}}{I_{BC}})M_{B} + \frac{L_{BC}}{I_{BC}}M_{C} = \frac{6E\Delta_{C/B}}{L_{BC}} - \frac{6E\Delta_{B/A}}{L_{AB}} - \frac{L_{AB}}{I_{AB}}(\Omega_{AB} + 2\Omega_{BA}) - \frac{L_{BC}}{I_{BC}}(2\Omega_{BC} + \Omega_{CB})$$
[13]

Let's see how Equation [13] can be used to analyze continuous beams with support reactions.

Example 1: Consider the beam shown below. Suppose the support at B has settled 10 mm. We wish to calculate the support reactions due to the settlement without considering the applied loads. The beam has a constant EI in which E is 200 GPa, and  $I = 0.0001 \text{ m}^4$ .



Figure 4: A two-span continuous beam

We start by drawing the internal moments at the supports, as shown below.



Figure 5: Internal bending moments in a two-span beam

In this case, since there is a pin at A and a roller at C,  $M_A = M_C = 0$ . Furthermore, since we are not considering the effect of the applied loads on the support reaction forces, all the fixed-end moment terms in Equation [13] are assumed to be zero. Therefore, the three-moment equation can be written in the simplified form shown below.

$$2(\frac{L_{AB}}{I_{AB}} + \frac{L_{BC}}{I_{BC}})M_{B} = \frac{6E\Delta_{C/B}}{L_{BC}} - \frac{6E\Delta_{B/A}}{L_{AB}}$$
[14]

To determine  $\Delta_{A/B}$  and  $\Delta_{C/B}$ , we need to examine each beam segment separately. Segment AB rotates clockwise as a result of the settlement at support B (see Figure 6). And since clockwise is considered negative direction for rotation according to the slope-deflection sign convention,  $\Delta_{B/A}$  is negative. That is,  $\Delta_{B/A} = -10 \text{ mm} = -0.01 \text{ m}$ .



Figure 6: Segment rotations in a two-span beam due to a support settlement

And since segment BC rotates counterclockwise due to the settlement at B,  $\Delta_{C/B}$  is considered positive. Hence,  $\Delta_{C/B} = 0.01 \text{ m}$ . Consequently, Equation [14] can be expanded as follows.

$$2(\frac{10}{0.0001} + \frac{10}{0.0001})M_{\rm B} = \frac{6(200 \times 10^9)(0.01)}{10} - \frac{6(200 \times 10^9)(-0.01)}{10}$$
[15]

Solving Equation [15] for  $M_B$ , we get:  $M_B = 6000 \text{ N.m.}$ , or  $M_B = 6 \text{ kN.m.}$ 

Figure 7 shows the resulting free-body diagrams for Segments AB and BC.



Figure 7: Internal bending moments in a two-span beam

The above diagrams can be used to calculate the member-end shear forces. This is done by writing and solving the static equilibrium equations for each segment. For segment AB, the equations can be written in the following manner.

$$6 - 10 V_{BA} = 0$$
 [16]

$$V_{AB} - V_{BA} = 0$$
 [17]

Solving the above equations for the two shear forces, we get:  $V_{BA} = 0.6 \text{ kN}$  and  $V_{AB} = 0.6 \text{ kN}$ . Similarly, the equilibrium equations for segment BC are as follows.

$$6 - 10V_{BC} = 0$$
 [18]

$$V_{CB} - V_{BC} = 0$$
 [19]

Equations [18] and [19] yield:  $V_{BC} = 0.6 \text{ kN}$  and  $V_{CB} = 0.6 \text{ kN}$ .

The reaction force at A equals  $V_{AB}$ . At B, the reaction force is the sum of  $V_{BA}$  and  $V_{BC}$ . And at C, the reaction equals  $V_{CB}$ . The following diagram shows the support reactions due to the settlement at B.



Figure 8: Support reaction due to a support settlement in a two-span beam

Example 2: Consider the beam shown below. It rests on a fixed support at A and on rollers at B and C. Suppose the support at B has a downward settlement of 10 mm, and the support at C has settled 4 mm. We wish to calculate the support reactions due to the applied load and the settlements. The beam has a constant EI in which E is 200 GPa and  $I = 0.0001 \text{ m}^4$ .



Figure 9: A continuous beam with a fixed support

To use the three-moment equation, we need to replace the fixed support at A with a fictitious infinitely rigid beam segment (see Figure 10).



Figure 9: A continuous beam with a fictitious infinitely rigid beam segment

Now we can write two three-moment equations: one equation for the left two segments and another equation for the right two segments.

For the left two segments, Equation [13] can be written as shown below.

$$\frac{L_{A_{0}A}}{I_{A_{0}A}}M_{A_{0}} + 2(\frac{L_{A_{0}A}}{I_{A_{0}A}} + \frac{L_{AB}}{I_{AB}})M_{A} + \frac{L_{AB}}{I_{AB}}M_{B} = \frac{6E\Delta_{B/A}}{L_{AB}} - \frac{6E\Delta_{A/A_{0}}}{L_{A_{0}A}} - \frac{L_{A_{0}A}}{I_{A_{0}A}}(\Omega_{A_{0}A} + 2\Omega_{AA_{0}}) - \frac{L_{AB}}{I_{AB}}(2\Omega_{AB} + \Omega_{BA})$$
[20]

Since  $M_{A_0} = 0$ ,  $I_{A_0A} = \infty$ , and fixed-end moments  $\Omega_{A_0A}$ ,  $\Omega_{AA_0}$ ,  $\Omega_{AB}$  and  $\Omega_{BA}$  are zero, the above equation simplifies to Equation [21].

$$2(\frac{L_{AB}}{I_{AB}})M_{A} + \frac{L_{AB}}{I_{AB}}M_{B} = \frac{6E\Delta_{B/A}}{L_{AB}} - \frac{6E\Delta_{A/A_{0}}}{L_{A_{0}A}}$$
[21]

Assuming that  $\delta_{A_0}$ ,  $\delta_A$ , and  $\delta_B$  are vertical settlements at supports  $A_0$ , A, and B respectively, we can determine  $\Delta_{A/A_0}$  and  $\Delta_{B/A}$  using the following equations.

$$\Delta_{A/A_0} = \delta_A - \delta_{A_0} = 0 - 0 = 0$$
[22]

$$\Delta_{\rm B/A} = \delta_{\rm A} - \delta_{\rm B} = (-0.01) - 0 = -0.01$$
[23]

By substituting the values for  $\Delta_{A/A_0}$ ,  $\Delta_{B/A}$ ,  $I_{AB}$ ,  $L_{AB}$ , and E in Equation [21], the following equation results.

$$2(\frac{4}{0.0001})M_{\rm A} + \frac{4}{0.0001}M_{\rm B} = \frac{6(200 \times 10^6)(-0.01)}{4}$$
 [24]

In its simplified form, Equation [24] turns into Equation [25], which is one of the two equations we need to solve the problem.

$$2M_{A} + M_{B} = -75$$
 [25]

The three-moment equation for the two right segments is shown below.

$$\frac{L_{AB}}{I_{AB}}M_{A} + 2(\frac{L_{AB}}{I_{AB}} + \frac{L_{BC}}{I_{BC}})M_{B} + \frac{L_{BC}}{I_{BC}}M_{C} = \frac{6E\Delta_{C/B}}{L_{BC}} - \frac{6E\Delta_{B/A}}{L_{AB}} - \frac{L_{AB}}{I_{AB}}(\Omega_{AB} + 2\Omega_{BA}) - \frac{L_{BC}}{I_{BC}}(2\Omega_{BC} + \Omega_{CB})$$
[26]

Since segment BC is subjected to a distributed load, the fixed-end moments for the segment are not zero; instead, they are:  $\Omega_{BC} = \Omega_{CB} = (3)(6^2)/12 = 9$  kN.m. However, the fixed-end moments for segment AB are zero, as the segment is not subjected to any loads. Therefore, we can write:  $\Omega_{AB} = \Omega_{BA} = 0$ .

Furthermore,  $\Delta_{\rm B/A}$  and  $\Delta_{\rm C/B}$  can be calculated as shown below.

$$\Delta_{\rm B/A} = \delta_{\rm B} - \delta_{\rm A} = (-0.01) - 0 = -0.01$$
[27]

$$\Delta_{C/B} = \delta_{C} - \delta_{B} = (-0.004) - (-0.01) = 0.006$$
[28]

After making the necessary substitutions in Equation [26], the following equation results.

$$\frac{4}{0.0001}M_{\rm A} + 2(\frac{4}{0.0001} + \frac{6}{0.0001})M_{\rm B} = 6(200 \times 10^6)(\frac{0.006}{6} + \frac{0.01}{4}) - \frac{6}{0.0001}(2 \times 9 + 9)$$
[29]

Which can be simplified to:

$$M_{A} + 5M_{B} = 64.5$$
 [30]

By solving Equations [25] and [30] simultaneously, we can determine  $M_A$  and  $M_B$  as follows:  $M_A = -44.83$  kN.m and  $M_B = 22.67$  kN.m. Now the resulting free-body diagrams for the two beam segments can be drawn as shown below.



Figure 10: Internal bending moments in a continuous beam with a fixed end

Using the static equilibrium equations, we can determine the member-end shear forces and the support reactions for the beam. Figure 11 shows the resulting reaction forces for the beam.



Figure 11: Support reactions for a continuous beam with a fixed end